

# Lecture 11: The firm and the investment decision: The Tobin's Q model

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# 11. The firm and the investment decision

- Firms produce goods.
- To produce, firms need production factors. They rent the production factors to the households.
- We assume that the objective of the firms is profit maximization. They maximize profits subject to a technological restriction.
- From the maximization problem we will obtain the rent prices for the production factors (given the technological restriction) and the level of production.

# 11. The firm and the investment decision

- Two approaches:
  - Neoclassical model: The optimal investment path depends on the optimal capital stock path as a function of the relative prices for the production factors.
  - The Tobin "Q" theory. The optimal investment path depends on the so-called Q ratio. The Q ratio is calculated as the market value of a company divided by the replacement value of the firm's assets.

# 11. The firm and the investment decision

- Technology: Aggregate production function:

$$Y_t = F(K_t, L_t) \quad (1)$$

- $Y_t$ : Output.
- Technology function has the following properties:

$$F_K > 0, F_L > 0 \quad (2)$$

$$F_{KK} < 0, F_{LL} < 0 \quad (3)$$

$$F_{KL} > 0 \quad (4)$$

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- Inada conditions:

$$\lim_{K \rightarrow 0} F_K = \infty, \lim_{K \rightarrow \infty} F_K = 0 \quad (5)$$

$$\lim_{L \rightarrow 0} F_L = \infty, \lim_{L \rightarrow \infty} F_L = 0 \quad (6)$$

To produce, the economy need a combination of the two production factors (labor and capital).

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- Profit maximization (The price is normalized to 1):

$$\max \Pi_t = Y_t - W_t L_t - R_t K_t \quad (7)$$

subject to:

$$Y_t = F(K_t, L_t) \quad (8)$$

- Assuming constant return to scale and perfect competition we have:  
 $\Pi_t = 0$ .
- First order conditions:

$$F_K(K_t, L_t) - R_t = 0 \quad (9)$$

$$F_L(K_t, L_t) - W_t = 0 \quad (10)$$

- Relative price for the production factors is equal to their marginal productivity.

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- Example: Cobb-Douglas production function:

$$F(K_t, L_t) = A_t K_t^\alpha L_t^{1-\alpha} \quad (11)$$

- $A_t$ : Total Factor Productivity.
- $\alpha$  : elasticity of output with respect to the capital.
- Important: The technological parameter also indicates the proportion of capital income over total income (capital compensation).  $1 - \alpha$  would be the proportional of labor income over total income (compensation on employees or labor compensation).

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- First order conditions:

$$\alpha A_t K_t^{\alpha-1} L_t^{1-\alpha} - R_t = 0 \quad (12)$$

$$(1 - \alpha) A_t K_t^{\alpha} L_t^{-\alpha} - W_t = 0 \quad (13)$$

- Or:

$$R_t = \frac{\alpha A_t K_t^{\alpha} L_t^{1-\alpha}}{K_t} = \alpha \frac{Y_t}{K_t} \quad (14)$$

$$W_t = \frac{(1 - \alpha) A_t K_t^{\alpha} L_t^{1-\alpha}}{L_t} = (1 - \alpha) \frac{Y_t}{L_t} \quad (15)$$



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- Decreasing marginal productivity conditions:

$$F_{KK} = (\alpha - 1)\alpha A_t K_t^{\alpha-2} L_t^{1-\alpha} < 0 \quad (16)$$

$$F_{LL} = -\alpha(1 - \alpha)A_t K_t^{\alpha} L_t^{-\alpha-1} < 0 \quad (17)$$

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- Profits are zero:

$$\Pi_t = A_t K_t^\alpha L_t^{1-\alpha} - R_t K_t - W_t L_t \quad (18)$$

$$\Pi_t = A_t K_t^\alpha L_t^{1-\alpha} - \alpha A_t K_t^{\alpha-1} L_t^{1-\alpha} - (1-\alpha) A_t K_t^\alpha L_t^{-\alpha} = 0 \quad (19)$$

# 11. The firm and the investment decision

- Profits:

$$\Pi_t = Y_t - W_t L_t - P_t^K K_t \quad (20)$$

- Physical capital accumulation equation in continuous time:

$$I_t = \dot{K}_t + \delta K_t \quad (21)$$

- If the firm is the owner of the capital stock, the profit function must be defined as:

$$\Pi_t = Y_t - W_t L_t - P_t^K I_t \quad (22)$$

- Price of capital is normalized to 1, ( $P_t^K = 1$ ).

# 11. The Tobin's Q model

- In the neoclassical model it is assumed that capital stock can be changed from one period to another without any restriction.
- In practice, capital accumulation process is subject to implicit costs: Capital adjustment costs or investment adjustment costs.
- Two types of adjustment costs:
  - External adjustment costs (the price of capital depends on the velocity of installation of the new capital.
  - Internal adjustment costs (a reduction in production and profits).

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- Internal adjustment costs:
  - Perfect elastic supply of capital.
  - Acquisition of new capital can be done at different speeds.
  - Price of capital is a function of the speed. Higher speed larger the price.
  - Example: Public infrastructure.

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- Internal adjustment costs:
  - When new capital is installed, a portion of inputs already used in the production, basically labor, must be devoted to the installation process.
  - These inputs will be not available to produce during the installation process, which implies forgone output.

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- Adjustment cost specification:

$$C = C(I_t, K_t) \quad (23)$$

$$\Psi(I_t, K_t) = I_t - C(I_t, K_t) \quad (24)$$

- The capital stock accumulation equation can be defined as:

$$K_{t+1} = (1 - \delta)K_t + I_t - C(I_t, K_t) = (1 - \delta)K_t + \Psi(I_t, K_t) \quad (25)$$

- Alternatively, we can assume that the adjustment cost is an additional cost to investment that implies a loss in output and hence in profits. In this case, capital accumulation equation is the standard, and profit function would be defined as:

$$\Pi_t = Y_t - W_t L_t - I_t - C(I_t, K_t) \quad (26)$$

# 11. The Tobin's Q model

- Properties of the adjustment costs function:

$$C(0, K_t) = 0 \quad (27)$$

$$C(I_t, 0) = 0 \quad (28)$$

$$C_I(I_t, K_t) > 0 \quad (29)$$

$$C_K(I_t, K_t) > 0 \quad (30)$$

$$C_{II}(I_t, K_t) > 0 \quad (31)$$

$$C_{KK}(I_t, K_t) > 0 \quad (32)$$



# 11. The Tobin's Q model

- Definition of the ratio Q: The Q ratio is calculated as the market value of a company divided by the replacement value of the firm's assets.

$$Q = \frac{MV}{KRV} \quad (33)$$

# 11. The Tobin's Q model

Estructure of the Tobin's Q model	
Firm's profits	$\Pi_t = Y_t - W_t L_t - I_t - C(I_t, K_t)$
Technology	$Y_t = F(K_t, L_t)$
Capital accumulation	$K_{t+1} = (1 - \delta)K_t + I_t$
Adjustment cost	$C = C(I_t, K_t)$
Initial capital stock	$K_0 > 0$
Ratio Q	$Q_t = \frac{V_t}{K_t}$

# 11. The Tobin's Q model

- The intertemporal profit maximization problem for the firms can be defined as:

$$\max E_t \sum_{t=0}^T \frac{1}{(1 + R_t)^t} \Pi_t \quad (34)$$

subject to the technological restriction and to the capital accumulation equation:

$$Y_t = F(K_t, L_t) \quad (35)$$

$$K_{t+1} = (1 - \delta)K_t + I_t \quad (36)$$

where the discount factor is the real interest rate,  $R_t$ ,  $E_t$  is the expectation operator, and where  $K_0 > 0$ , and known. Additionally, the following condition must be hold:

$$\lim_{T \rightarrow \infty} K_T = \bar{K} \quad (37)$$

where  $\bar{K}$  is the steady state capital stock.

# 11. The Tobin's Q model

- Intertemporal profit maximization problem:

$$\max \sum_{t=0}^T \frac{1}{(1 + R_t)^t} [Y_t - W_t L_t - I_t - C(I_t, K_t)] \quad (38)$$

subject to the above restrictions. By substituting the technological restriction into the objective function (profits), we obtain the following auxiliary Lagrangian function:

$$\begin{aligned} V = & \sum_{t=0}^T \frac{1}{(1 + R_t)^t} [F(K_t, L_t) - W_t L_t - I_t - C(I_t, K_t)] \\ & - \lambda_t (K_{t+1} - I_t - (1 - \delta)K_t) \end{aligned} \quad (39)$$

# 11. The Tobin's Q model

- First order conditions:

$$\frac{\partial V}{\partial K_{t+1}} : \frac{1}{(1 + R_{t+1})^{t+1}} [F_K(K_{t+1}, L_{t+1}) - C_K(I_{t+1}, K_{t+1})] + \lambda_{t+1}(1 - \delta) - \lambda_t = 0 \quad (40)$$

$$\frac{\partial V}{\partial I_t} : -\frac{1 + C_I(I_t, K_t)}{(1 + R_t)^t} + \lambda_t = 0 \quad (41)$$

$$\frac{\partial V}{\partial L_t} : \frac{F_L(K_t, L_t) - W_t}{(1 + R_t)^t} = 0 \quad (42)$$

$$\frac{\partial V}{\partial \lambda_t} : -K_{t+1} + I_t + (1 - \delta)K_t = 0 \quad (43)$$

# 11. The Tobin's Q model

- From the first order condition (41) we obtain the Lagrange multiplier for period  $t$ :

$$\lambda_t = \frac{1 + C_I(I_t, K_t)}{(1 + R_t)^t} \quad (44)$$

and for period  $t + 1$ :

$$\lambda_{t+1} = \frac{1 + C_I(I_{t+1}, K_{t+1})}{(1 + R_{t+1})^{t+1}} \quad (45)$$

## 11. The Tobin's Q model

- Given that the real interest rate (the discount factor) is a exogenous variable, we assume that  $R_{t+1} = R_t$ . By substituting the Lagrange multiplier in the first order condition (40), we have:

$$F_K(K_{t+1}, L_{t+1}) - C_K(I_{t+1}, K_{t+1}) = (1 + R_t) [1 + C_I(I_t, K_t)] - [1 + C_I(I_{t+1}, K_{t+1})] (1 - \delta) \quad (46)$$

where the value of the marginal product of capital is equal to the cost of use (this is the investment decision by the firm).

- Finally, from the first order condition (42) we obtain the condition that equals labor marginal productivity with the salary:

$$F_L(K_t, L_t) = W_t \quad (47)$$

# 11. The Tobin's Q model

- Next, we define the variable  $q$ . The ratio  $q$  is defined as:

$$q_t = \lambda_t (1 + R_t)^t \quad (48)$$

Therefore, the shadow price of capital can be defined as:

$$\lambda_t = \frac{q_t}{(1 + R_t)^t} \quad (49)$$

and using the definition for the Lagrange multiplier yields,

$$q_t = 1 + C_I(I_t, K_t) \quad (50)$$



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- By substituting in the equilibrium condition for the capital stock (46), we obtain:

$$F_K(K_{t+1}, L_{t+1}) - C_K(I_{t+1}, K_{t+1}) = (1 + R_t) q_t - q_{t+1}(1 - \delta) \quad (51)$$

From the above expression we obtain the following dynamic equation for the marginal ratio  $q$ :

$$q_{t+1} = \frac{(1 + R_t)q_t - F_K(K_{t+1}, L_{t+1}) + C_K(I_{t+1}, K_{t+1})}{1 - \delta} \quad (52)$$

Without adjustment costs,  $C_K(I_{t+1}, K_{t+1}) = 0$ , the dynamic equation for the marginal ratio  $q$  should be:

$$q_{t+1} = \frac{(1 + R_t)q_t - F_K(K_{t+1}, L_{t+1})}{1 - \delta} \quad (53)$$

# 11. The Tobin's Q model

- In sum, the Tobin's  $Q$  model can be defined as a two-equation dynamic system for the capital stock and for the ratio  $q$ , given by:

$$q_t = 1 + C_I(I_t, K_t) \quad (54)$$

$$(1 - \delta)q_{t+1} + F_K(K_{t+1}, L_{t+1}) = (1 + R_t)q_t + C_K(I_{t+1}, K_{t+1}) \quad (55)$$

plus a static equilibrium condition for labor. By assuming that labor is constant, the Tobin's  $Q$  model de Tobin lo podemos resolver en términos del stock de capital y la ratio  $q$ . El stock de capital es una variable de estado, que viene predeterminada por las decisiones tomadas en el periodo anterior, mientras que la ratio  $q$  es una variable flexible, que está sujeta a cambios en las expectativas, y que se ajusta de forma instantánea ante perturbaciones.

# 11. The Tobin's Q model

- Example:
- Labor is normalized to 1 ( $L_t = 1$ ). Production function is given by:

$$Y_t = F(K_t) = K_t^\alpha \quad (56)$$

where  $0 < \alpha < 1$ .

- Adjustment cost function:

$$C(I_t, K_t) = \frac{\phi}{2} \left( \frac{I_t - \delta K_t}{K_t} \right)^2 K_t \quad (57)$$

depending on both capital stock and investment and where  $\phi > 0$  is a parameter governing the elasticity of investment with respect to the ratio  $q$ .

# 11. The Tobin's Q model

- In this particular case, we have that:

$$C_I(I_t, K_t) = \phi \left( \frac{I_t - \delta K_t}{K_t} \right) \quad (58)$$

$$C_K(I_t, K_t) = \frac{\phi}{2} \left( \frac{I_t - \delta K_t}{K_t} \right)^2 - \phi \left( \frac{I_t - \delta K_t}{K_t} \right) \frac{I_t}{K_t} \quad (59)$$

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- By substituting in the model solution:

$$q_t = 1 + \phi \left( \frac{I_t - \delta K_t}{K_t} \right) \quad (60)$$

$$\begin{aligned} (1 - \delta)q_{t+1} = & (1 + R_t)q_t - \alpha K_{t+1}^{\alpha-1} + \frac{\phi}{2} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right)^2 \\ & - \phi \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right) \frac{I_{t+1}}{K_{t+1}} \end{aligned} \quad (61)$$

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- From the above expression, we can derive the two dynamic equations of the model. From the capital stock accumulation equation we have that:

$$I_t - \delta K_t = K_{t+1} - K_t \quad (62)$$

Defining  $\Delta K_t = K_{t+1} - K_t$ , and substituting in expression (60), we have the following expression:

$$q_t - 1 = \phi \frac{\Delta K_t}{K_t} \quad (63)$$

and operating yields:

$$\Delta K_t = (q_t - 1) \frac{K_t}{\phi} \quad (64)$$

# 11. The Tobin's Q model

- On the other hand, operating in expression (61) and defining  $\Delta q_t = q_{t+1} - q_t$ , we have that:

$$\begin{aligned} q_{t+1} = & \frac{(1 + R_t)}{(1 - \delta)} q_t - \frac{\alpha}{(1 - \delta)} K_{t+1}^{\alpha-1} + \frac{\phi}{2(1 - \delta)} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right)^2 \\ & - \frac{\phi}{(1 - \delta)} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right) \frac{I_{t+1}}{K_{t+1}} \end{aligned} \quad (65)$$

# 11. The Tobin's Q model

- Adding and subtracting  $q_t$  in the lhs of the above expression:

$$q_{t+1} - q_t + q_t = \frac{(1 + R_t)}{(1 - \delta)} q_t - \frac{\alpha}{(1 - \delta)} K_{t+1}^{\alpha-1} + \frac{\phi}{2(1 - \delta)} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right)^2 - \frac{\phi}{(1 - \delta)} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right) \frac{I_{t+1}}{K_{t+1}}$$

and operating yields:

$$\Delta q_t = \frac{(R_t + \delta) q_t - \alpha K_{t+1}^{\alpha-1} + \frac{\phi}{2} \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right)^2 - \phi \left( \frac{I_{t+1} - \delta K_{t+1}}{K_{t+1}} \right) \frac{I_{t+1}}{K_{t+1}}}{(1 - \delta)} \quad (67)$$



# 11. The Tobin's Q model

- Steady state
- The dynamic equation for the capital stock (the investment rule), in steady state, is given by:

$$\Delta K_t = (\bar{q} - 1) \frac{\bar{K}}{\phi} = 0 \quad (68)$$

Given that in steady state the above equation must be zero, the steady state value for the ratio  $q$  is one:

$$\bar{q} = 1 \quad (69)$$

In fact, in steady state  $C_I(\cdot) = 0$ , and therefore  $\bar{q} = 1$ .

# 11. The Tobin's Q model

- On the other hand, the dynamic equation for the ratio  $q$ , in steady state, is given by:

$$\Delta q_t = \frac{(R_t + \delta)\bar{q} - \alpha \bar{K}^{\alpha-1}}{(1 - \delta)} = 0 \quad (70)$$

given that in steady state  $\bar{I}_t = \delta \bar{K}_t$ . Therefore,:

$$\alpha \bar{K}^{\alpha-1} = R_t + \delta \quad (71)$$

and thus the capital stock in steady state is given by:

$$\bar{K} = \left( \frac{R_t + \delta}{\alpha} \right)^{\frac{1}{\alpha-1}} \quad (72)$$